On Identity Testing and Noncommutative Rank Computation over the Free Skew Field

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Abstract

The identity testing of rational formulas (RIT) in the free skew field efficiently reduces to computing the rank of a matrix whose entries are linear polynomials in noncommuting variables [22]. This rank computation problem has deterministic polynomial-time white-box algorithms [19, 24] and a randomized polynomial-time algorithm in the black-box setting [13]. In this paper, we propose a new approach for efficient derandomization of *black-box* RIT. Additionally, we obtain results for matrix rank computation over the free skew field, and construct efficient linear pencil representations for a new class of rational expressions. More precisely, we show the following results:

- Under the hardness assumption that the ABP (algebraic branching program) complexity of every polynomial identity for the $k \times k$ matrix algebra is $2^{\Omega(k)}$ [8], we obtain a subexponential-time black-box algorithm for RIT in almost general setting. This can be seen as the first "hardness implies derandomization" type theorem for rational formulas.
- We show that the noncommutative rank of any matrix over the free skew field whose entries have small linear pencil representations can be computed in deterministic polynomial time. Prior to this, an efficient rank computation was only known for matrices with noncommutative formulas as entries [18]. As special cases of our algorithm, we obtain the first deterministic polynomial-time algorithms for rank computation of matrices whose entries are noncommutative ABPs or rational formulas.
- Motivated by the definition given by Bergman [6], we define a new class of rational functions where a rational function of inversion height at most h is defined as a composition of a noncommutative r-skewed circuit (equivalently an ABP) with inverses of rational functions of this class of inversion height at most h-1 which are also disjoint. By definition, this class contains ABPs and rational formulas. We obtain a polynomial-size linear pencil representation for this class. As a by-product, we obtain a white-box deterministic polynomial-time identity testing algorithm for the class.

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1 Introduction

In algebraic circuit complexity the basic arithmetic operations are additions, multiplications, and inverses. Using these arithmetic operations algebraic circuits compute either polynomials or rational functions. An important sub-area of algebraic complexity is *noncommutative computation* where the multiplication of variables is not commutative and the set of monomials (over the variables) form a free monoid. If we allow only addition and multiplication gates in the noncommutative case) in the free algebra.

In the commutative case, the role of inverses is well understood but in the noncommutative world it is quite subtle. To elaborate, it is known that any commutative rational expression can be expressed as fg^{-1} where f and g are two commutative polynomials [32]. However, noncommutative rational expressions such as $x^{-1} + y^{-1}$ or $xy^{-1}x$ cannot be represented as fg^{-1} or $f^{-1}g$. If we have nested inverses then it makes the rational expression more complicated, for example $(z + xy^{-1}x)^{-1} - z^{-1}$. Moreover, a noncommutative rational expression is not always defined on a matrix substitution. For a noncommutative rational expression \mathfrak{r} , its domain of definition is the set of matrix tuples (of any dimension) where \mathfrak{r} is defined. We denote it by dom(\mathfrak{r}). Two rational expressions \mathfrak{r}_1 and \mathfrak{r}_2 are equivalent if they agree on dom(\mathfrak{r}_1) \cap dom(\mathfrak{r}_2). This induces an equivalence relation on the set of all noncommutative rational expressions (with nonempty domain of definition). It was used by Amitsur in his characterization of the universal free skew field (denoted by $\mathbb{F} \boldsymbol{<} x \boldsymbol{>}$ when the variable set is $x = \{x_1, x_2, \ldots, x_n\}$) and the equivalence classes are called the noncommutative rational functions [1]. This object plays an important role in the study of noncommutative algebra [1, 11], control theory [26], and algebraic automata theory [34].

Computationally, rational functions are represented by noncommutative arithmetic circuits or formulas using addition, multiplication, and inverse gates [22]. The *inversion height* of a rational formula is the maximum number of inverse gates in a path from an input gate to the output gate. It is known that the inversion height of a rational formula of size s is bounded by $O(\log s)$ [22]. Hrubeš and Wigderson consider the *rational identity testing* problem (RIT) of testing the equivalence of two rational formulas [22]. It is the same as testing whether a rational formula computes the zero function in the free skew field. In other words, decide whether there exists a matrix tuple (of any dimension) such that the rational formula evaluates to nonzero on that substitution. Rational expressions exhibit peculiar properties which seem to make the RIT problem quite different from polynomial identity testing. The apparent lack of *canonical representations* such as the sum of monomials representation for polynomials and the use of nested inverses in noncommutative rational expressions complicate the problem. For example, the rational expression $(x + xy^{-1}x)^{-1} + (x + y)^{-1} - x^{-1}$ of inversion height two is a rational identity, known as Hua's identity [23].

A second characterization of the free skew field entries was developed by Cohn [11]. A linear pencil L of size s over noncommuting variables $x = \{x_1, \ldots, x_n\}$ is a $s \times s$ matrix whose entries are linear forms in \underline{x} variables, i.e. $L = A_0 + \sum_{i=1}^n A_i x_i$, where each A_i is an $s \times s$ matrix over the field \mathbb{F} . Cohn showed that for every free skew field entry \mathfrak{r} in $\mathbb{F} \langle x \rangle$, there is a linear pencil L such that \mathfrak{r} is an entry of the inverse of L. More generally, we say that \mathfrak{r} has a linear pencil representation of size s, if for vectors $\underline{c}, \underline{b} \in \mathbb{F}^s$ and $s \times s$ linear pencil L, $\mathfrak{r} = \underline{c}^t L^{-1}\underline{b}$ where \underline{c}^t is the transpose of \underline{c} . Hrubeš and Wigderson give an efficient reduction from the RIT problem to the singularity testing problem of linear pencils [22]. In particular, if \mathfrak{r} is a rational formula of size s, they showed that \mathfrak{r} has a linear pencil representation L of size at most 2s such that \mathfrak{r} is defined on a matrix tuple if and

only if L is invertible on that tuple [22]. Using this connection, they reduce the RIT problem to the problem of testing whether a given linear pencil is invertible over the free skew field in deterministic polynomial time. The latter is the noncommutative SINGULAR problem, whose commutative analog is the symbolic determinant identity testing problem. The deterministic complexity of symbolic determinant identity testing has deterministic polynomial-time algorithms in the SINGULAR problem in noncommutative setting has deterministic polynomial-time algorithms in the white-box model due to the works of Garg et al. [19] which is based on *operator scaling* and that of Ivanyos et al. [24] which is based on the *second Wong sequence* and a constructive version of *regularity lemma*. As a consequence, a deterministic polynomial-time white-box RIT algorithm follows.

A central open problem in this area is to design an efficient *deterministic* algorithm for noncommutative SINGULAR problem in the black-box case [19]. The algorithms by Garg et al. [19] and Ivanyos et al. [24] are inherently sequential and we believe that they are unlikely to be helpful for black-box algorithm design. It is well-known [19] that an efficient black-box algorithm (via a hitting set construction) for SINGULAR would generalize the celebrated quasi-NC algorithm for bipartite matching significantly [16]. There is a randomized polynomial-time black-box algorithm for this problem [13].

Even for the RIT problem (which could be easier than the noncommutative SINGULAR problem), the progress towards designing efficient deterministic black-box algorithm is very limited. In fact, only very recently a deterministic quasipolynomial-time black-box algorithm for identity testing of rational formulas of *inversion height two* has been designed [2]. It is interesting to note that in the literature of identity testing, the noncommutative SINGULAR problem and the RIT problem stand among rare examples where deterministic polynomial-time white-box algorithms are designed but for the black-box case no deterministic *subexponential-time* algorithm is known.

Remark 1. For noncommutative polynomials computed by polynomial-size arithmetic circuits, efficient randomized polynomial identity testing algorithms are known either for polynomial degree bound or for exponential sparsity bound [8, 4]. In contrast, the complexity of testing the identity of rational circuits is completely open. In fact, even in the white-box setting we do not have a randomized subexponential-time algorithm.

1.1 Derandomization of RIT from the hardness of polynomial identities

In this paper, we propose a new approach to tackle the RIT problem in the black-box case under a suitable hardness assumption, which is a known conjecture in theory of Polynomial Identities (PI). This was first raised by Bogdanov and Wee [8, Section 6.2].

Conjecture 2. The ABP complexity (i.e. the minimum size of an algebraic branching program) of a polynomial identity for the $k \times k$ matrix algebra $\mathbb{M}_k(\mathbb{F})$ is $2^{\Omega(k)}$.

The conjecture implies that ABPs of size s cannot evaluate to zero on all $O(\log s)$ -dimensional matrices. Bogdanov and Wee [8] also observed that if the conjecture holds then there is an $s^{O(\log^2 s)}$ -time black-box PIT for noncommutative ABPs¹ and as supportive evidence showed that the conjecture is indeed true for normal identities (of which the standard identity is a special case), and the identity of algebraicity.

¹Independent of the conjecture, Forbes-Shpilka [17] obtained an $s^{O(\log s)}$ -time black-box PIT for noncommutative ABPs.

Consider the following variant of the usual hitting set definition.

Definition 3. For a class of rational formulas \mathcal{R} , we say that a hitting set \mathcal{H} is *strong* if for any formula $\mathfrak{r} \in \mathcal{R}$, there exists a matrix tuple $p \in \mathcal{H}$ such that $\mathfrak{r}(p)$ is invertible.

In the following theorem, we show that an efficient derandomization of RIT is possible assuming Conjecture 2. This can be seen as the first "hardness implies derandomization" type result for rational formulas.

Theorem 4. If Conjecture 2 is true then we can construct a strong hitting set of size $(snh(\gamma \log s)^{2h+2})^{O(h(\gamma \log s)^{2h+2})}$ for rational formulas \mathfrak{r} of size s over n variables and inversion height h in deterministic $(snh(\gamma \log s)^{2h+2})^{O(h(\gamma \log s)^{2h+2})}$ -time for some constant $\gamma > 1$. This result holds over infinite or sufficiently large finite fields and $h \leq \beta(\log s/\log \log s)$ for any $0 < \beta < 1$.

As a special case for h = O(1), this gives a quasipolynomial-size hitting set. To get a subexponential-size bound $2^{s^{\delta}}$ on the hitting set where δ is any constant in (0, 1), we can allow $h \leq c_{\delta}(\log s/\log \log s)$. Here $c_{\delta} \in (0, 1)$ is a constant that depends on δ .

As already mentioned, the inversion height of size s rational formula is bounded by $O(\log s)$ [22]. Therefore, Theorem 4 solves the RIT problem in an almost general setting.

We believe that the main interesting point about Theorem 4 is that it relates the black-box RIT derandomization that involves handling *nested inverses* with a problem purely for noncommutative polynomials: we can obtain a deterministic black-box RIT algorithm by showing an exponential size lower bound for ABPs computing any polynomial identity for matrix algebras. Over the years such hardness assumptions have proved to be useful in designing deterministic algorithms for problems related to identity testing [20, 25, 5, 14, 10, 28].

1.1.1 Proof Sketch

The first step in proving Theorem 4 is a variable reduction step that shows the identity testing of a rational formula \mathfrak{r} of inversion height h can be reduced to the identity testing of another rational formula \mathfrak{r}' over 2(h+1) variables in a black-box manner. Notice that for noncommutative polynomials (for which h = 0), such a reduction is standard and given by $x_i \to y_0 y_1^i y_0$ where y_0, y_1 are new noncommutative variables. We prove it by induction on h. In fact, we use a stronger inductive hypothesis that roughly says that for every nonzero rational formula \mathfrak{r} of inversion height h, there also exists a 2(h+1)-tuple of matrices tuple $(q_{00}, \ldots, q_{h0}, q_{01}, \ldots, q_{h1})$ such that $\mathfrak{r}(p_1, \ldots, p_n)$ is invertible and for each $i \in [n]$, $p_i = \sum_{j=0}^{h} q_{j0} q_{j1}^i q_{j0}$. Once we assume the inductive hypothesis for inversion height h - 1, for each rational formula \mathfrak{r} of inversion height h, we get a matrix tuple of the form $\underline{p} = (p_1, \ldots, p_n)$ where $p_i = \sum_{j=0}^{h-1} q_{j0} q_{j1}^i q_{j0}$ such that \mathfrak{r} is defined on \underline{p} . Then, we use concepts from matrix coefficient realization theory and construct the nonzero generalized series $\mathfrak{r}(\underline{x} + \underline{p})$ [34]. Now, we can use the standard bivariate encoding trick on $\mathfrak{r}(\underline{x} + \underline{p})$ to complete the variable-reduction step.

The next important step that we establish is that if Conjecture 2 is true then for any rational formula \mathfrak{r} of size s and inversion height h, one can find a matrix tuple \underline{p} of dimension $(\gamma \log s)^{h+1}$ (for some constant γ) such that $\mathfrak{r}(\underline{p})$ is an invertible matrix. This is done via induction on h and a bootstrapping argument. For the base case, we take h = 0. In this case the rational formula is also an ABP of size s and Conjecture 2 confirms that \mathfrak{r} is nonzero on a generic matrix tuple \underline{p} of dimension $O(\log s)$. Also $\mathfrak{r}(\underline{p})$ is invertible by an application of Amitsur's theorem [1]. Inductively we assume that we can find such a matrix tuple q of dimension $d_{h-1} \leq (\gamma \log s)^h$ for any rational

formula \mathfrak{r} of inversion height at most h-1 and size at most s. An easy observation shows that given a rational formula \mathfrak{r} of inversion height h, \mathfrak{r} is defined on such a matrix tuple \underline{q} . We again use matrix coefficient realization theory[34] to construct the nonzero generalized series $\mathfrak{r}(\underline{x} + \underline{q})$ by expanding \mathfrak{r} around the point \underline{q} . Substituting the variables x_1, x_2, \ldots, x_n by symbolic generic matrices over noncommuting variables $Z^{(1)}, \ldots, Z^{(n)}$ of dimension d_{h-1} , we observe that each entry of the output matrix $\mathfrak{r}(\underline{Z} + \underline{q})$ is a recognizable series computed by a small size algebraic automaton.

By a standard result in algebraic automata theory generally attributed to Schützenberger [15, Corollary 8.3, Page 14], we know that at least one of the series is nonzero even when we truncate it to a small degree. Applying the Conjecture 2, we infer that the truncated series is nonzero on generic matrices of dimension roughly $\approx \log(sd_{h-1})$. A simple scaling trick shows that the full (infinite)series is also nonzero on generic matrices of same dimension. This determines the dimension of the generic matrices on which the rational formula \mathfrak{r} is nonzero. Moreover the rational formula evaluates to an invertible matrix on generic matrix substitution of that dimension. This is a consequence of Amitsur's theorem [1].

Once we have these two steps, the rest of the proof is straightforward. Given nonzero \mathfrak{r} over the variables x_1, \ldots, x_n of height h, we apply the variable reduction step to construct nonzero \mathfrak{r}' of height h (and roughly of same size) over 2(h+1) variables $\{y_{00}, y_{01}, \ldots, y_{h0}, y_{h1}\}$. Now we apply the second step that says that \mathfrak{r}' is nonzero (and hence invertible) on generic matrices over Z variables of dimension $(\gamma \log s)^{h+1}$. We also make use of the fact that $\mathfrak{r}'(\underline{y})$ has a small-size linear pencil. To construct the final hitting set, we just need to hit two sparse polynomials of sparsity bound roughly $(snh(\gamma \log s)^{2h+2})^{O(h(\gamma \log s)^{2h+2})}$ and this can be done by applying the standard result of sparse polynomial hitting set construction [27].

1.2 Noncommutative rank of matrices over the free skew field

For a matrix $M = (g_{i,j})_{m \times m}$ over the free skew field $\mathbb{F} \not\langle \underline{x} \rangle$, its noncommutative rank(denoted by ncrank(M)) is the least positive integer $r \leqslant m$ such that M = PQ for an $m \times r$ matrix P and an $r \times m$ matrix Q over $\mathbb{F} \not\langle \underline{x} \rangle$. This is also called the *inner rank*. If r = m, then M is invertible in $\mathbb{F} \not\langle \underline{x} \rangle$.

Indeed, a fundamental result of Cohn [12] showed that for any matrix $M = (g_{i,j})_{m \times m}$ over the noncommutative ring $\mathbb{F}\langle \underline{x} \rangle$ such that $\operatorname{ncrank}(M) = r$, there exists an $m \times r$ matrix P and an $r \times m$ matrix Q over $\mathbb{F}\langle \underline{x} \rangle$.

As already mentioned, the problem of computing the noncommutative rank of a linear matrix admits deterministic polynomial-time white-box algorithms [19, 24]. If the matrix entries consist of some higher degree terms, one can use Higman's trick [21] to reduce it to computing rank of a linear matrix. Consider the following well-known example of a 2×2 matrix [18]:

$$\begin{bmatrix} 1 & x \\ y & z + xy \end{bmatrix}.$$

Higman's trick reduces it to another 3×3 linear matrix preserving the complement of the noncommutative rank in the following way:

$$\begin{bmatrix} 1 & x \\ y & z + xy \end{bmatrix} \mapsto \begin{bmatrix} 1 & x & 0 \\ y & z + xy & 0 \\ 0 & 0 & 1 \end{bmatrix} \mapsto \begin{bmatrix} 1 & x & 0 \\ y & z & x \\ 0 & -y & 1 \end{bmatrix}.$$

However, it would not be efficient in general. In [18, Proposition A.2], the authors showed an effective use of Higman's trick to efficiently reduce it to the rank computation of a linear matrix when the entries are computed by noncommutative *formulas*.

In this paper, we address the matrix rank computation over the free skew field in a very general setting. In particular, we obtain an efficient reduction to the rank computation of a linear matrix even when the entries are free skew field elements computed by small linear pencils. More precisely, we show the following.

Theorem 5. Let $M = (g_{i,j})_{m \times m}$ be a matrix such that for each $i, j \in [m]$, $g_{i,j}$ in $\mathbb{F} \langle x_1, \ldots, x_n \rangle$ has a linear pencil of size at most s. Then, the noncommutative rank of M can be computed in deterministic poly(m, n, s) time. Moreover, in deterministic poly(m, n, s) time, we can output a matrix tuple $\underline{T} = (T_1, \ldots, T_n)$ of dimension d such that the matrix the rank of matrix $M(\underline{T})$ is $d \cdot \operatorname{ncrank}(M)$. The field \mathbb{F} could be infinite or sufficiently large finite field.

As any noncommutative formula has a small linear pencil, our result subsumes a particular result of Garg et al. [18] which shows the efficient matrix rank computation when the entries are noncommutative formulas. If the entries of the matrices are computed by noncommutative ABPs, by a direct application of the algorithm due to Garg et al. [18] we can compute the rank in deterministic quasipolynomial time as any ABP has a quasipolynomial-size formula. However, since a noncommutative ABP has a polynomial-size linear pencil [22], as a direct corollary of Theorem 5, we obtain a deterministic poly(m, n, s)-time algorithm for the ABP case. Moreover, since noncommutative rational formulas also have polynomial-size linear pencils [22], we obtain a deterministic poly(m, n, s)-time algorithm even if each entry of the matrix is computed by a rational formula.

1.2.1 Proof Sketch

The basic principle of our proof is to reduce the problem to the rank computation of a linear matrix. However, there is no clear notion of *degree reduction* for arbitrary elements over the free skew field. This forces us to find a new approach of constructing this linear matrix efficiently that can also handle a matrix of skew field entries as input. The main idea of the proof is to show that the linear pencil representation enjoys the following closure property. Let A be an $m \times m$ generic matrix over m^2 indeterminates and let substituting each indeterminate of A by a free skew field entry that also has a linear pencil of size at most s, we obtain M. We show that we can find a small linear matrix L efficiently such that ncrank $(L) = m^2 s + ncrank(M)$. Somewhat surprisingly, the construction of L turned out to be relatively simple and elegant.

There are many equivalent notions of noncommutative rank for linear matrices (for example, see [24, 19]). A notion of particular interest is the blow-up definition that is crucial in the algorithm of Ivanyos et al. [24]. The blow-up notion enables to find a matrix tuple on which the maximum rank is achieved. We extend this notion and introduce a blow-up definition for noncommutative rank (denoted by ncrank^{*}) of matrices with free skew field entries. We show that for any matrix M of free skew field entries, ncrank(M) = ncrank^{*}(M). Introduction of the blow-up definition allows us to find efficiently the matrix tuple \underline{T} of dimension d such that the rank of $M(\underline{T})$ is $d \cdot \text{ncrank}(M)$. One can view the blow-up definition in this case as an extension of the theory developed by Derksen and Makam [13] for the linear case. This extension could be of independent mathematical interest.

1.3 Linear pencil representations for a new class of rational functions

The study of linear pencils seem to be the key in understanding several basic questions in rational function theory [22, 18, 24, 34, 13]. In this section, our main motivation is to understand the relation between the linear pencil representations of rational functions and the representations using basic arithmetic operations. Let RF, LR, RC be the class of polynomial-size rational formulas, the class of rational functions that have polynomial-size linear pencil representations, and the class of polynomial-size rational circuits. Hrubeš and Wigderson [22] prove an exponential size lower bound on the size of the rational formulas computing an entry of the inverse of a symbolic matrix. Moreover, they show that each entry of the inverse of a symbolic matrix is computable by a rational circuit of polynomial size. Therefore, the current known relation is RF \subset LR \subseteq RC.

Following Bergman [6], a noncommutative rational function $\mathfrak{r}(\underline{x})$ of inversion height at most h can be inductively defined as $\mathfrak{r}(\underline{x}) = f(x_1, \ldots, x_n, g_1^{-1}, \ldots, g_m^{-1})$, where f is a noncommutative polynomial and $g_1, \ldots, g_m \in \mathbb{F} \lt \underline{x} >$ are rational functions of inversion height $\leqslant h - 1$. Using this, we give the following definition.

Definition 6. A rational r-skewed circuit of inversion height 0 is a noncommutative r-skewed circuit² which is also a noncommutative ABP. Inductively, we define $\mathbf{r}(\underline{x}) = f(x_1, \ldots, x_n, g_1^{-1}, \ldots, g_m^{-1})$ as a rational r-skewed circuit of inversion height at most h if $f(\underline{x}, y_1, \ldots, y_m)$ is a noncommutative r-skewed circuit $(m \ge 0)$ and for each $i \in [m], g_i(\underline{x})$ is a rational r-skewed circuit of inversion height k = 1.

Let R-rSC be the class of all rational functions computable by polynomial-size rational r-skewed circuits. Inspecting the polynomial size rational circuit for symbolic matrix inverse [22], one can notice that each entry of the inverse of a polynomial-size symbolic matrix can indeed be computed by a polynomial-size rational r-skewed circuit. Hence $LR \subseteq R-rSC$. What is the exact expressive power of the class LR? In particular, is it true that LR = R-rSC? It now suffices to show that $R-rSC \subseteq LR$. While we are unable to answer this completely, we exhibit such a containment under additional structural restriction.

Definition 7. An inversely disjoint rational r-skewed circuit of inversion height 0 is a noncommutative r-skewed circuit (which is also an ABP). Inductively, we define $\mathfrak{r}(\underline{x}) = f(x_1, \ldots, x_n, g_1^{-1}, \ldots, g_m^{-1})$ as an inversely disjoint rational r-skewed circuit of inversion height at most h if $f(\underline{x}, y_1, \ldots, y_m)$ is a noncommutative r-skewed circuit ($m \ge 0$) and for each $i \in [m], g_i(\underline{x})$ is a inversely disjoint rational r-skewed circuit of inversion height $i \ne j$, the circuits of g_i and g_j are disjoint.

Let ID-R-rSC be the class of rational functions computed by polynomial-size *inversely disjoint r-skewed circuits*. This class contains rational formulas, ABPs. We are able to give polynomial-size linear pencil representations for this class.

Theorem 8. Over any field, an inversely disjoint rational r-skewed circuit of size s has a linear pencil representation of size $O(s^2)$ which can be computed in deterministic polynomial time from the given circuit.

This gives the following containment:

 $\mathsf{RF}\subseteq\mathsf{ID}\text{-}\mathsf{R}\text{-}\mathsf{r}\mathsf{SC}\subseteq\mathsf{LR}\subseteq\mathsf{R}\text{-}\mathsf{r}\mathsf{SC}\subseteq\mathsf{RC},$

²Usually in the literature they are called right-skew circuits. For the purpose of this paper, we prefer referring to them as *right-skewed* and reserve the word "skew" for the *skew field*.

where we know at least one of the first two containment is proper. We do not know any unconditional separation between RF and ID-R-rSC. This question is somewhat similar in spirit to the separation of noncommutative formulas and ABPs which is still open [30, 9, 33]. However, a simple inductive argument shows that a function of inversion height h in ID-R-rSC can be computed by rational formula of size $s^{O(h \log s)}$. By the standard argument, a noncommutative r-skewed circuit of size s can be computed by a formula of size $s^{O(\log s)}$. Consider an inversely disjoint r-skewed circuit $\mathfrak{r}(x, g_1^{-1}, \ldots, g_m^{-1})$ where each $g_i \in \text{ID-R-rSC}$ of inversion height $\leqslant h - 1$ for each $1 \leqslant i \leqslant m$. Inductively, each g_i has a rational formula of size $s^{O((h-1)\log s)}$. Therefore, the size of the rational formula computing \mathfrak{r} can be at most $s^{O(h\log s)}$. If $h = O(\log s)$, we then have a quasipolynomial-size formula simulation for this class. However, unlike rational formulas [22], it is not clear whether hcan be taken as $O(\log s)$ for a general inversely disjoint r-skewed circuit of size s.

Using Theorem 8, the following corollary is obtained by the application of rank computation algorithm in [24]. For the black-box case, we can apply the algorithm in [13]. In the proof of the corollary we also mention how to apply the algorithm in [24] for the black-box case and get an efficient randomized algorithm over the finite fields also.

Corollary 9. Let \mathbb{F} be infinite or any sufficiently large field. For an inversely disjoint rational *r*-skewed circuit of size at most *s* and over *n* variables, we can decide whether it computes zero in $\mathbb{F} \not{\langle} \underline{x} \not{\rangle}$ or not in deterministic poly(s, n) time in white-box, and in randomized poly(s, n) time in black-box.

1.3.1 Proof Sketch

As the key component, the proof uses a composition lemma that computes an efficient linear pencil for $f(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ from the linear pencils of $f(\underline{x}, \underline{y})$ and $g_1^{-1}, \ldots, g_m^{-1}$. It turns out that the proof of this composition result is more subtle than the usual proofs of the linear pencil constructions for rational formulas [22, 34].

We first elaborate on the composition lemma. Let L be an $s \times s$ linear pencil over x_1, \ldots, x_n and y_1, \ldots, y_m . Let $f_{i,j} = (L^{-1})_{i,j}$ for $i, j \in [s]$. Let g_1, \ldots, g_m be rational functions over x_1, \ldots, x_n such that each g_k has a linear pencil L_k of size at most s'. Then we can construct a single linear pencil \widetilde{L} of size at most $ms' + m + 2s^2 + s$ in poly(s', s, m, n)-time such that

$$(\widetilde{L}^{-1})_{2s^2+\widehat{s}+i,2s^2+\widehat{s}+j} = f_{i,j}(\underline{x}, g_1^{-1}, \dots, g_m^{-1}) \text{ for } i, j \in [s], \text{ where } \widehat{s} = ms' + m.$$

Given a rational function \mathfrak{r} computed by an inversely disjoint rational r-skewed circuit of size at most s, we consider the rational function \mathfrak{r}^{-1} which is still in the same class (with inversion height increased by one). Using the composition result, we construct a linear pencil of size $O(s^2)$ for \mathfrak{r}^{-1} . Notice that $\mathfrak{r}(\underline{x},\underline{y})$ is a polynomial computed by an ABP or a r-skewed circuit and it has a polynomial-size linear pencil [22]. Using a standard idea, \mathfrak{r}^{-1} also has a small linear pencil L which we use as the input to the composition lemma along with the inductively constructed linear pencils for g_1, \ldots, g_m .

The final linear pencil \widetilde{L} which is the outcome of the composition lemma has the additional property that for any matrix tuple $\mathfrak{r}(\underline{p})$, $\mathfrak{r}^{-1}(\underline{p})$ is defined if and only if $\widetilde{L}(\underline{p})$ is invertible. Since $\mathfrak{r} \neq 0$ if and only if \mathfrak{r}^{-1} is defined [1], we can now use the algorithm for noncommutative SINGULAR problem [24] on the linear pencil \widetilde{L} to check the identity of \mathfrak{r} .

Organization

In Section 2, we mainly provide brief background on linear pencils and its connection with the rational identity testing problem, and also present some results in matrix coefficient realization theory. We prove Theorem 4 in Section 3. The proof of Theorem 5 is given in Section 4.2. We give the proof of Theorem 8 in Section 5. We state some open questions in Section 6.

2 Preliminaries

2.1 Linear pencils and rational functions

Let \mathbb{F} be a field. A linear pencil L of size s over noncommuting $\underline{x} = \{x_1, \ldots, x_n\}$ variables is a $s \times s$ matrix where each entry is a linear form in \underline{x} . That is, $L = A_0 + \sum_{i=1}^n A_i x_i$ where each A_i in $\mathbb{M}_s(\mathbb{F})$. Evaluation of a linear pencil at a matrix tuple $\underline{p} = (p_1, \ldots, p_n)$ in $\mathbb{M}_m^n(\mathbb{F})$ is defined using the Kronecker (tensor) product: L evaluated at p is $A_0 \otimes I_m + \sum_{i=1}^n A_i \otimes p_i$.

Given a linear pencil L, the noncommutative SINGULAR problem is to decide whether there is a tuple \underline{p} in $\mathbb{M}_m^n(\mathbb{F})$ of $m \times m$ matrices for some m such that the output matrix L evaluated at \underline{p} is invertible.

A rational function \mathfrak{r} in $\mathbb{F} \not < \underline{x} \rightarrow$ has a linear pencil representation L of size s if $\mathfrak{r} = \underline{c}^t L^{-1} \underline{b}$ for vectors $\underline{c}, \underline{b} \in \mathbb{F}^s$. Following is the re-statement of Proposition 7.1 proved in [22].

Proposition 10. Let \mathfrak{r} be a rational function given by a rational formula of size s. Then \mathfrak{r} can be represented $(L^{-1})_{i,j}$ for $i, j \in [s]$ where L is a linear pencil of size at most 2s. Moreover, \mathfrak{r} is nonzero if and only if L is invertible.

Clearly in the above proposition the choice for $\underline{c}, \underline{b}$ are the indicator vectors e_i and e_j . We also use the following classical result of Amitsur [1] in this paper.

Theorem 11 ([1]). Let \mathfrak{r} be a rational function which is nonzero on $\mathbb{M}_k(\mathbb{F})$ where \mathbb{F} is infinite or any sufficiently large field. Then $\mathfrak{r}(Y_1, \ldots, Y_n)$ is an invertible matrix in $\mathbb{M}_k(\mathbb{F}(Y))$ where Y_1, \ldots, Y_n are generic indeterminate matrices of dimension k.

Remark 12. Usually Theorem 11 is stated over infinite fields. However it can be adapted over any sufficiently large finite field \mathbb{F} using the techniques in [24]. We briefly discuss it here. For details we refer the reader to ALGORITHM 1 in [24]. Define the field \mathbb{F}' by adjoining a k^{th} root ζ to \mathbb{F} i.e. $\mathbb{F}' = \mathbb{F}[\zeta]$. Then construct a $\mathbb{F}'(Z_1, Z)$ basis $\Gamma = \{C_1, \ldots, C_{k^2}\}$ of $\mathbb{M}_k(\mathbb{F}'(Z_1, Z))$ such that $\mathbb{F}'(Z_1, Z^k)$ -linear span of Γ is a central division algebra over $\mathbb{F}'(Z_1, Z^k)$. Here Z_1, Z are two independent formal variables. Using that we can see that \mathfrak{r} is invertible on a generic linear combination of Γ . Now by a standard argument the generic variables can be fixed from \mathbb{F} (assuming that \mathbb{F} is sufficiently large) to obtain a matrix tuple T such that $\mathfrak{r}(T)$ is invertible. This also implies that $\mathfrak{r}(Y)$ is invertible where Y is a generic matrix tuple of dimension k.

2.2 Algebraic branching programs (ABPs)

Definition 13. An algebraic branching program (ABP) is a layered directed acyclic graph with one in-degree-0 vertex called *source*, and one out-degree-0 vertex called *sink*. Its vertex set is partitioned into layers $0, 1, \ldots, d$, with directed edges only between adjacent layers (i to i + 1). The source and the sink are in layers zero and d, respectively. Each edge is labeled by a linear

form over \mathbb{F} in variables $\{x_1, \ldots, x_n\}$. The polynomial computed by the ABP is the sum over all source-to-sink directed paths of the product of linear forms that label the edges of the path. The maximum number of nodes in any layer is called the width of the algebraic branching program. The size of the branching program is taken to be the total number of nodes.

Equivalently, an ABP of width w and d many layers can be defined as an entry of a product of d many linear matrices of size at most w. Therefore, the polynomial f computed by an ABP is of form $(M_1 \cdots M_d)_{i,j}$ for some $i, j \in [w]$.

Proposition 14. An ABP of size s has a linear pencil of size at most 2s from the following construction:

$$L_{f} = \begin{bmatrix} I_{w} & -M_{1} & & \\ & I_{w} & -M_{2} & \\ & & \ddots & \ddots & \\ & & & I_{w} & -M_{d} \\ & & & & I_{w} \end{bmatrix}$$

The ABP is computed in the upper right corner.

This construction is well-known and also used in [22].

2.3 Matrix Inverse

Let P be a 2×2 block matrix shown below.

$$P = \begin{bmatrix} p_1 & p_2 \\ p_3 & p_4 \end{bmatrix}$$

where p_1 is invertible and p_2 and p_3 can be any rectangular matrices and $(p_4 - p_3 p_1^{-1} p_2)$ is also invertible. Then we note that the inverse of P has the following structure [22].

$$P^{-1} = \begin{bmatrix} p_1^{-1}(I + p_2(p_4 - p_3p_1^{-1}p_2)^{-1}p_3p_1^{-1}) & -p_1^{-1}p_2(p_4 - p_3p_1^{-1}p_2)^{-1} \\ -(p_4 - p_3p_1^{-1}p_2)^{-1}p_3p_1^{-1} & (p_4 - p_3p_1^{-1}p_2)^{-1} \end{bmatrix}$$
(1)

If $p_3 = 0$, then P^{-1} has a simpler structure.

$$P^{-1} = \begin{bmatrix} p_1^{-1} & -p_1^{-1}p_2p_4^{-1} \\ 0 & p_4^{-1} \end{bmatrix}.$$
 (2)

Hrubeš and Wigderson use Equation 1 to compute each entry of the matrix inverse recursively by a small rational circuit.

Theorem 15. [22, Theorem 2.4] Each entry of an $s \times s$ symbolic matrix is computable by a rational circuit of size $O(s^{\omega})$ where ω is the exponent of matrix multiplication.

Remark 16. We observe that the same construction also yields a polynomial-size rational r-skewed circuit as defined in Definition 6 for the matrix inverse. Inspecting Equation 1, we just need to compute the entries of p_1^{-1} and $(p_4 - p_3 p_1^{-1} p_2)^{-1}$ and after that the remaining computation is straightforward. Notice that, in the composition step while replacing each y_i by g_i^{-1} , Definition 6 allows any g_i to be a sub-circuit of some g_j . Therefore, we can reuse the r-skewed circuit computing each entry of p_1^{-1} and follow the same recursive construction to obtain a rational r-skewed circuit of size $O(s^{\omega})$.

2.4 Recognizable series

A comprehensive treatment is in the book by Berstel and Reutenauer [7]. We will require the following concepts. Recall that $\mathbb{F}\langle\!\langle \underline{x} \rangle\!\rangle$ is the formal power series ring over a field \mathbb{F} . A series S in $\mathbb{F}\langle\!\langle \underline{x} \rangle\!\rangle$ is *recognizable* if it has the following linear representation: for some integer s, there exists a row vector $\underline{c} \in \mathbb{F}^{1 \times s}$, a column vector $\underline{b} \in \mathbb{F}^{s \times 1}$ and an $s \times s$ matrix M whose entries are homogeneous linear forms over x_1, \ldots, x_n i.e. $\sum_{i=1}^n \alpha_i x_i$ such that $S = \underline{c}^t \left(\sum_{k \ge 0} M^k \right) \underline{b}$. Equivalently, $S = \underline{c}^t (I - M)^{-1} \underline{b}$. We say, S has a representation $(\underline{c}, M, \underline{b})$ of size s^{-3} .

The following theorem is a basic result in algebraic automata theory.

Theorem 17. A recognizable series with representation $(\underline{c}, M, \underline{b})$ of size s is nonzero if and only if $\underline{c}^t (\sum_{k \leq s-1} M^k) \underline{b}$ is nonzero.

It has a simple linear algebraic proof [15, Corollary 8.3, Page 145]. This result is generally attributed to Schützenberger. For the purpose of this paper, the theorem is used to apply that the truncated series is computable by a small noncommutative ABP therefore reducing zero-testing of recognizable series to the identity testing of noncommutative ABPs.

2.5 Matrix coefficient realization theory

The noncommutative rational functions lack a canonical form. If a noncommutative rational function is analytic (or defined) at a matrix point, then (matrix coefficient)-realization theory offers a representation of the noncommutative rational function around that point. This is also common in automata theory and control theory. For a detailed exposition of this theory, see the work of Volčič [34].

Recall that, $\mathbb{M}_m(\mathbb{F})$ is the $m \times m$ matrix algebra over \mathbb{F} . A generalized word or a generalized monomial in x_1, \ldots, x_n over $\mathbb{M}_m(\mathbb{F})$ allows the matrices to interleave between variables. More formally, a generalized word over $\mathbb{M}_m(\mathbb{F})$ is of the following form: $a_0 x_{k_1} a_2 \cdots a_{d-1} x_{k_d} a_d$ where $a_i \in \mathbb{M}_m(\mathbb{F})$. A generalized polynomial over $\mathbb{M}_m(\mathbb{F})$ is obtained by a finite sum of generalized monomials in the ring $\mathbb{M}_m(\mathbb{F})\langle \underline{x} \rangle$. Similarly, a generalized series over $\mathbb{M}_m(\mathbb{F})$ is obtained by infinite sum of generalized series over $\mathbb{M}_m(\mathbb{F})$ is obtained by infinite sum of generalized monomials in the ring $\mathbb{M}_m(\mathbb{F})\langle \underline{x} \rangle$.

A generalized series (resp. polynomial) S over $\mathbb{M}_m(\mathbb{F})$ admits the following canonical description. Let $E = \{e_{i,j}, 1 \leq i, j \leq m\}$ be the set of matrix units. Express each coefficient matrix a in S in the E basis by a \mathbb{F} -linear combination and then expand S. Naturally each monomial of degree-d in the expansion looks like $e_{i_0,j_0}x_{k_1}e_{i_1,j_1}x_{k_2}\cdots e_{i_{d-1},j_{d-1}}x_{k_d}e_{i_d,j_d}$ where $e_{i_l,j_l} \in E$ and $x_{k_l} \in x$. We say the series S (resp. polynomial) is identically zero if and only if it is zero under such expansion i.e. the coefficient associated with each generalized monomial in the canonical representation is zero.

The evaluation of a generalized series over $\mathbb{M}_m(\mathbb{F})$ is defined on any $k'm \times k'm$ matrix algebra for some integer $k' \ge 1$ [34]. To match the dimension of the coefficient matrices with the matrix substitution, we use an inclusion map $\iota : \mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{k'm}(\mathbb{F})$, for example, ι can be defined as $\iota(a) = a \otimes I_{k'}$ or $\iota(a) = I_{k'} \otimes a$. We now define the evaluation of a generalized series (resp. polynomial) over $\mathbb{M}_m(\mathbb{F})$ in the following way. Any degree-*d* generalized word $a_0 x_{k_1} a_1 \cdots a_{d-1} x_{k_d} a_d$ over $\mathbb{M}_m(\mathbb{F})$ on a matrix substitution $(p_1, \ldots, p_n) \in \mathbb{M}^n_{k'm}(\mathbb{F})$ evaluates to

$$\iota(a_0)p_{k_1}\iota(a_1)\cdots\iota(a_{d-1})p_{k_d}\iota(a_d)$$

³In the language of weighted automata, the matrix M is the transition matrix for the series S.

under some inclusion map $\iota : \mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{k'm}(\mathbb{F})$. In ring theory, all such inclusions are known to be compatible by the Skolem-Noether theorem [31, Theorem 3.1.2]. Therefore, if a series S is zero with respect to some inclusion map $\iota : \mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{k'm}(\mathbb{F})$, then it must be zero w.r.t. any such inclusions. The equivalence of the two notions of zeroness follows from the proof of [34, Proposition 3.13].

We now recall the definition of a recognizable generalized series from the same paper.

Definition 18. A generalized series S in $\mathbb{M}_m(\mathbb{F})\langle\!\langle x \rangle\!\rangle$ is *recognizable* if it has the following linear representation. For some integer s, there exists a row-tuple of matrices $\mathbf{c} \in (\mathbb{M}_m(\mathbb{F}))^{1\times s}$, and $\mathbf{b} \in (\mathbb{M}_m(\mathbb{F}))^{s\times 1}$ and an $s \times s$ matrix M whose entries are homogeneous generalized linear forms over x_1, \ldots, x_n i.e. $\sum_{i=1}^n p_i x_i q_i$ where each $p_i, q_i \in \mathbb{M}_m(\mathbb{F})$ such that $S = \mathbf{c}(I - M)^{-1}\mathbf{b}$. We say, S has a linear representation $(\mathbf{c}, M, \mathbf{b})$ of size s over $\mathbb{M}_m(\mathbb{F})$.

In [34], Volčič shows the following result.

Theorem 19. [34, Corollary 5.1, Proposition 3.13] Given a noncommutative rational formula \mathfrak{r} of size s over x_1, \ldots, x_n and a matrix tuple $\underline{p} \in \mathbb{M}_m^n(\mathbb{F})$ in the domain of definition of \mathfrak{r} , $\mathfrak{r}(\underline{x} + \underline{p})$ is a recognizable generalized series with a representation of size at most 2s over $\mathbb{M}_m(\mathbb{F})$. Additionally, $\mathfrak{r}(\underline{x})$ is zero in the free skew field if and only if $\mathfrak{r}(\underline{x} + p)$ is zero as a generalized series.

Proof. For the first part, see Corollary 5.1 and Remark 5.2 of [34].

To see the second part, let $\mathfrak{r}(\underline{x})$ is zero in the free skew field. Then the fact that $\mathfrak{r}(\underline{x} + \underline{p})$ is a zero series follows from Proposition 3.13 of [34]. If $\mathfrak{r}(\underline{x})$ is nonzero in the free skew field, then there exists a matrix tuple $(q_1, \ldots, q_n) \in \mathbb{M}_l^n(\mathbb{F})$ such that $\mathfrak{r}(\underline{q})$ is nonzero. W.l.o.g. we can assume l = k'm for some integer k'. Fix an inclusion map $\iota : \mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{k'm}(\mathbb{F})$. Define a matrix tuple $(q'_1, \ldots, q'_n) \in \mathbb{M}_{k'm}^n(\mathbb{F})$ such that $q'_i = q_i - \iota(p_i)$. Therefore, the series $\mathfrak{r}(\underline{x} + \underline{p})$ on (q'_1, \ldots, q'_n) evaluates to $\mathfrak{r}(\underline{q})$ under the inclusion map ι , hence nonzero [34, Remark 5.2]. Therefore, $\mathfrak{r}(\underline{x} + \underline{p})$ is also nonzero.

Remark 20. More explicitly we can say the following which is already outlined in [34, Section 5]. For inclusion map $\iota : \mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{k'm}(\mathbb{F})$

$$\mathfrak{r}(\underline{q}+\iota(\underline{p}))=\iota(\boldsymbol{c})\left(I_{2sk'm}-\sum_{j=1}^{n}\iota(A^{x_j})(\underline{q})\right)^{-1}\iota(\boldsymbol{b}).$$

We also note down a few basic facts. The following is easy to show and also noted in [34].

Fact 21. Let $\mathfrak{r}(\underline{x} + \underline{p})$ be a generalized series where \underline{p} consists of matrices in $\mathbb{M}_m(\mathbb{F})$. If we replace each x_i by a generic matrix over noncommuting variables $(y_{j,k}^i)_{1 \leq j,k \leq m}$, then we get a nonzero matrix over the \underline{y} variables. More precisely, the map $\psi(x_i) = (y_{j,k}^i)_{1 \leq j,k \leq m}$ is identity preserving.

Another easy fact is the following.

Fact 22. Let $\mathfrak{r}(\underline{x} + \underline{p})$ has a linear representation $\mathbf{c}(I - M)^{-1}\mathbf{b}$ of size s. Then each entry of $\mathfrak{r}(\psi(\underline{x}) + \underline{p})$ is a recognizable series with transition matrix $M(\psi(x_1), \ldots, \psi(x_n))$ of size sm. More precisely, the $(i, j)^{th}$ entry of $\mathfrak{r}(\psi(\underline{x}) + \underline{p})$ has a representation $(\underline{c}_i, M(\psi(\underline{x})), \underline{b}_j)$ where \underline{c}_i and \underline{b}_j are the *i*th row and *j*th column of \mathbf{c} and \mathbf{b} repectively.

3 Derandomization of RIT from the Hardness of Polynomial Identities

In this section, we present a new approach to derandomize (almost general) RIT efficiently in the black-box setting and prove Theorem 4. Given a noncommutative polynomial $P(x_1, \ldots, x_n) \in \mathbb{F}\langle x_1, \ldots, x_n \rangle$, there is a well-known trick to reduce the identity testing of P to the identity testing of a bivariate polynomial $P'(y_0, y_1)$ over the noncommuting variables y_0, y_1 by the substitution $x_i \leftarrow y_0 y_1^i y_0$ for $1 \leq i \leq n$.

For a rational formula $\mathfrak{r}(\underline{x})$, such a variable reduction step preserving identity is not immediate. Our first result in this section reduces the identity testing of an *n*-variate rational formula of inversion height *h* to the identity testing of a rational formula of inversion height *h* over 2(h + 1) variables. But before that we record a simple fact.

Fact 23. Given any rational formula \mathfrak{r}' of of inversion height at most h-1 and size at most s, if we can find a matrix tuple such that \mathfrak{r}' is invertible on that matrix tuple, then for a rational formula \mathfrak{r} of size at most s and inversion height h, we can find a matrix tuple where \mathfrak{r} is defined.

Proof. Let \mathcal{F} be the collection of all those inverse gates in the formula \mathfrak{r} such that for every $g \in \mathcal{F}$, the path from the root to g does not contain any inverse gate. For each $g_i \in \mathcal{F}$, let h_i be the sub-formula input to g_i . Consider the formula $\mathfrak{r}' = h_1 h_2 \cdots h_k$ (where $k = |\mathcal{F}|$) which is of size at most s since for each i and j, h_i and h_j are disjoint. Clearly, \mathfrak{r}' is of inversion height at most h-1. So if we find a point q such that $\mathfrak{r}'(q)$ is invertible then \mathfrak{r} is defined at that point q.

Now we state and prove the variable reduction lemma for rational formulas.

Lemma 24. Let $\mathfrak{r}(x_1, \ldots, x_n)$ be a rational formula of inversion height h. Then, there exists a 2(h+1) variate rational formula \mathfrak{r}' of inversion height h over the variables $\{y_{j0}, y_{j1} : 0 \leq j \leq h\}$ such that \mathfrak{r} is zero in $\mathbb{F} \boldsymbol{\langle} \boldsymbol{x} \boldsymbol{\rangle}$ if and only if \mathfrak{r}' is zero in $\mathbb{F} \boldsymbol{\langle} \boldsymbol{y} \boldsymbol{\rangle}$. Moreover, \mathfrak{r}' is obtained from \mathfrak{r} by substituting x_i by $\sum_{j=0}^h y_{j0} y_{j1}^i y_{j0}$ for $1 \leq i \leq n$.

Proof. The proof is by induction on the inversion height h. In fact we use a stronger inductive hypothesis: For every nonzero rational formula of inversion height h, there also exists a matrix tuple (p_1, \ldots, p_n) and a collection of matrices $\{q_{00}, \ldots, q_{h0}, q_{01}, \ldots, q_{h1}\}$ such that $\mathfrak{r}(p_1, \ldots, p_n)$ is invertible and for each $i \in [n]$, $p_i = \sum_{j=0}^{h} q_{j0} q_{j1}^i q_{j0}$.

It is true for noncommutative polynomials for which h = 0. It is already mentioned that the substitution $x_i \leftarrow y_0 y_1^i y_0$ reduces the identity testing of $P(\underline{x})$ to the identity testing of $P'(y_0, y_1)$. Moreover, by Theorem 11, we know that we can find matrices q_0, q_1 such that the bivariate polynomial $P'(q_0, q_1)$ evaluates to an invertible matrix. Since $P(q_0q_1q_0, q_0q_1^2q_0, \ldots, q_0q_1^nq_0) = P'(q_0, q_1)$, we establish the base case of the induction.

Inductively, suppose that it is true for any formula of inversion height h - 1. Now consider a nonzero rational formula $\mathfrak{r}(x_1, \ldots, x_n)$ of inversion height h. From the inductive hypothesis and Fact 23, there exists a matrix tuple (p_1, \ldots, p_n) and a collection of matrices $\{\tilde{q}_{00}, \ldots, \tilde{q}_{(h-1)0}, \tilde{q}_{01}, \ldots, \tilde{q}_{(h-1)1}\}$ such that $\mathfrak{r}(p_1, \ldots, p_n)$ is defined and for each $i \in [n]$, $p_i = \sum_{j=0}^{h-1} \tilde{q}_{j0} \tilde{q}_{j1}^i \tilde{q}_{j0}$. Let the dimension of each p_i be m. Therefore, $\mathfrak{r}(x+p)$ is also a nonzero generalized series by Theorem 19. Replacing each x_i by $y_0 y_1^i y_0$, we obtain a nonzero bivariate generalized series and suppose it is nonzero for $y_0 = \hat{q}_{h0}$ and $y_1 = \hat{q}_{h1}$ of some dimension km for an integer k. Notice from Section 2 that a generalized series is zero if and only if the coefficient of every monomial in

the canonical representation is zero. Therefore the bivariate substitution $x_i \rightarrow y_0 y_1^i y_0$ preserves the nonzeroness of a generalized series. Therefore,

$$\mathfrak{r}(\widehat{q_{h0}}\widehat{q_{h1}}\widehat{q_{h0}}+\iota(p_1),\ldots,\widehat{q_{h0}}\widehat{q_{h1}}^n\widehat{q_{h0}}+\iota(p_n))$$

is also nonzero. Notice that, $\iota(p_i) = \sum_{j=0}^{h-1} \iota(\tilde{q}_{j0})(\iota(\tilde{q}_{j1}))^i \iota(\tilde{q}_{j0})$ for the inclusion map ι from $\mathbb{M}_m(\mathbb{F}) \to \mathbb{M}_{km}(\mathbb{F})$. We can now define \mathfrak{r}' substituting each x_i in \mathfrak{r} by $\sum_{j=0}^h y_{j0} y_{j1}^i y_{j0}$. Clearly, \mathfrak{r}' is nonzero. By Theorem 11, \mathfrak{r}' is also invertible for some matrix tuple \underline{q} of same dimension. Hence $\mathfrak{r}(p_1,\ldots,p_n)$ is invertible for $p_i = \sum_{j=0}^h q_{j0} q_{j1}^i q_{j0}$.

Next we show that if Conjecture 2 is true then any rational formula of size s and inversion height $h \leq \beta(\log s/\log \log s)$ for $\beta \in (0, 1)$, is nonzero on a matrix tuple of dimension $(\gamma \log s)^{h+1}$ for some constant γ .

Lemma 25. Let $\mathfrak{r}(x_1, \ldots, x_n)$ be a nonzero rational formula of size s and inversion height $h \leq \beta(\log s/\log \log s)$ for any constant $0 < \beta < 1$. Then, Conjecture 2 implies that there is a matrix tuple $(p_1, \ldots, p_n) \in \mathbb{M}_m^n(\mathbb{F})$ such that $\mathfrak{r}(p_1, \ldots, p_n)$ is invertible and $m = (\gamma \log s)^{h+1}$ for some constant $\gamma > 1$.

Proof. The proof is by induction on h. For the base case h = 0, Conjecture 2 implies that the noncommutative formula is nonzero on generic $c \log s$ (for some constant c) dimensional matrix tuple (Z_1, \ldots, Z_n) where $Z_i = (z_{\ell,k}^{(i)})_{1 \leq \ell, k \leq c \log s}$. Also Theorem 11 says that the formula evaluates to an invertible matrix M(Z) on substituting x_i by Z_i . Now using standard idea, random substitution to the variables in Z_1, \ldots, Z_n yields such a matrix tuple.

Inductively assume that we have already proved the dimension bound on the witness of the invertible image for rational formulas of inversion height at most h - 1. Let the dimension of the matrices be d_{h-1} . Now given a rational formula \mathfrak{r} of size s and inversion height h, observe that \mathfrak{r} is defined on some $d_{h-1} \times d_{h-1}$ matrix tuple q using Fact 23.

Then by Theorem 19, $\mathfrak{r}(\underline{x} + \underline{q})$ can be represented by a recognizable generalized series of size at most 2s such that $\mathfrak{r}(\underline{x})$ is nonzero if and only if $\mathfrak{r}(\underline{x} + \underline{q})$ is nonzero. Using Fact 21, apply the ψ map on the variables such that $\psi(x_i)$ substitutes the variable x_i by a matrix of fresh noncommuting variables $z_{i,k}^{(i)}$ for $1 \leq j, k \leq d_{h-1}$.

Using Fact 22, observe that we get a matrix of recognizable series and each such recognizable series can be represented by an automaton of size at most $\hat{s} \leq 2sd_{h-1}$. Since ψ preserves identity, one of such recognizable series will be nonzero. So w.lo.g, let the series be $S_{1,1}$ computed at $(1,1)^{th}$ entry is nonzero. Let the transition matrix for $S_{1,1}$ is $M_{1,1}$. Then using Theorem 17, the truncated finite series $\tilde{S}_{1,1} = \underline{c}^t \left(\sum_{k \leq \hat{s}-1} M_{1,1}^k \right) \underline{b}$ is nonzero, which is a noncommutative ABP.

If Conjecture 2 is true then $\tilde{S}_{1,1}$ will be nonvanishing on a matrix tuple \underline{p} of dimension $O(\log \hat{s})$. Now by the following simple scaling trick, we show that the infinite series $S_{1,1}$ is nonzero at a matrix tuple of dimension $c \log \hat{s}$.

Claim 26. We can find a matrix tuple \underline{p}' which is a scalar multiple of \underline{p} such that $S_{1,1}(\underline{p}')$ is nonzero.

Proof. Let τ be a commutative variable and consider the matrix tuple,

$$\tau \underline{p} = (\tau p_{1,1}^{\{1\}}, \dots, \tau p_{d_{h-1}, d_{h-1}}^{\{1\}}, \dots, \tau p_{1,1}^{\{n\}}, \dots, \tau p_{d_{h-1}, d_{h-1}}^{\{n\}}).$$

Observe that $M_{1,1}(\tau p) = \tau M_{1,1}(p)$. From the definition of the series $S_{1,1}$,

$$S_{1,1}(\underline{z}) = \tilde{S}_{1,1}(\underline{z}) + \sum_{i \ge \hat{s}} \underline{c}^t M_{1,1}^i \underline{b}$$

Let d be the dimension of the matrices in the tuple \underline{p} . We now evaluate $S_{1,1}$ at $\tau \underline{p}$ to get the following:

$$S_{1,1}(\tau \underline{p}) = \tilde{S}_{1,1}(\tau \underline{p}) + \sum_{i \ge \hat{s}} \tau^i \cdot \left((\underline{c} \otimes I_d)^t \cdot M_{1,1}^i(\underline{p}) \cdot (\underline{b} \otimes I_d) \right).$$

Since $\tilde{S}_{1,1}(\underline{p}) \neq 0$, we have that $S_{1,1}(\tau \underline{p})$ evaluates to a nonzero matrix whose entries are power series in the variable τ .

It is also true that $S_{1,1}(\tau \underline{p}) = (\underline{c} \otimes I_d)^t \cdot (I - M_{1,1}(\tau \underline{p}))^{-1} \cdot (\underline{b} \otimes I_d)$ which is rational expression in τ where the degrees of the numerator and denominator polynomials are bounded by $poly(\hat{s}, d)$. Hence we need to avoid only $poly(\hat{s}, d)$ values for τ such that $S_{1,1}(\tau \underline{p})$ is defined and nonzero. \Box

The above argument shows that for a specific value τ_0 for the parameter τ , the generalized series $\mathfrak{r}(\underline{x} + \underline{q})$ evaluates to nonzero on a matrix tuple $(N_1(\tau_0) + \iota(q_1), \ldots, N_n(\tau_0) + \iota(q_n))$ where N_i is obtained from the matrix $(z_{j,k}^{(i)})_{1 \leq j,k \leq d_{h-1}}$ by substituting the variables $(z_{j,k}^{(i)})_{1 \leq j,k \leq d_{h-1}}$ by $\tau_0 p_{j,k}^{(i)}$. Also ι is the inclusion map $\iota : \mathbb{M}_{d_{h-1}}(\mathbb{F}) \to \mathbb{M}_{dd_{h-1}}(\mathbb{F})$ defined as $\iota(q_i) = q_i \otimes I_d$.

Hence \mathfrak{r} is nonzero on generic matrix tuples of dimension $d_h = dd_{h-1} \leq cd_{h-1}\log(sd_{h-1})$. Inductively assume that $d_{h-1} \leq (2c\log s)^h$. Since $h \leq \beta(\log s/\log \log s)$, we can observe that $s \geq d_{h-1}$. Using this we get that $d_h \leq c(2c\log s)^h \log(s^2)$ and that yields $d_h \leq (2c\log s)^{h+1}$. We take $\gamma = 2c$.

Therefore by Theorem 11 $\mathfrak{r}(\underline{x})$ evaluates to an invertible matrix on substituting x_i by generic matrices of dimension $(\gamma \log s)^{h+1}$.

Now we are ready to show that if Conjecture 2 is true, then we can find a subexponential-size hitting set for rational formulas of size s and inversion height up to $c'(\log s/\log \log s)$ for a suitable constant c' that depends on the exponent of the subexponential function.

Proof of Theorem 4. Let $\mathfrak{r}(x_1, \ldots, x_n)$ be a rational formula of inversion height h and size s. Consider, $\mathfrak{r}'(y_{00}, y_{01}, \ldots, y_{h0}, y_{h1})$ obtained from \mathfrak{r} by substituting x_i by $\sum_{j=0}^{h} y_{j0} y_{j1}^i y_{j0}$ for $1 \leq i \leq n$. From Lemma 24, we know that $\mathfrak{r}(\underline{x})$ is nonzero if and only if $\mathfrak{r}'(\underline{y})$ is nonzero. Moreover, \mathfrak{r}' has a rational formula of size at most s' which is of O(snh). Therefore, \mathfrak{r}' must be invertible on $d_h \times d_h$ generic matrix substitution where $d_h \leq (\gamma \log s')^{h+1}$ from Lemma 25. Using Proposition 10, we know that \mathfrak{r}' has a linear pencil L' of size at most 2s'. W.l.o.g, assume that \mathfrak{r}' is computed at the $(1,1)^{th}$ entry of L'^{-1} .

Hence, if we substitute the variables $y_{00}, y_{01}, \ldots, y_{0h}, y_{1h}$ by $d_h \times d_h$ generic matrices $\{Z^{(i,0)}, Z^{(i,1)} : 0 \leq i \leq h\}$ (over commuting variables), the $(1,1)^{th}$ block of $L'^{-1}(\mathbb{Z})$ will be of form $\frac{M'(\mathbb{Z})}{\det(L'(\mathbb{Z}))}$ where $\det(L'(\mathbb{Z}))$ is a polynomial of degree at most $2s'(\gamma \log s')^{h+1}$. Further, each entry of the matrix M' is a cofactor of $L'(\mathbb{Z})$ and therefore it is a polynomial over the \mathbb{Z} variables of degree at most $2s'(\gamma \log s')^{h+1}$. This shows that $\det(M'(\mathbb{Z}))$ is a nonzero polynomial of degree at most $2s'(\gamma \log s')^{h+2}$.

The sparsity of det($L'(\underline{Z})$) and det($M'(\underline{Z})$) are bounded by $\kappa = (s'(\gamma \log s)^{2h+2})^{O(h(\gamma \log s)^{2h+2})}$. Now we can use standard sparse polynomial hitting set for κ -sparse polynomials to hit both the polynomials [27]. This gives us a strong hitting set \mathcal{H}' for \mathfrak{r}' . Consequently, we get a strong hitting set of same size for \mathfrak{r} by using the substitutions of x_i variables by the $y_{00}, y_{01}, \ldots, y_{0h}, y_{1h}$ described in Lemma 24. More formally, we define

$$\mathcal{H}_{n,h,s} = \{(p_1, \dots, p_n) : \underline{q} \in \mathcal{H}'; p_i = \sum_{j=0}^h q_{j0} q_{j1}^i q_{j0} \}.$$

An immediate corollary is the following.

Corollary 27. The hitting set size and the construction time is $s^{(\log s)^{O(1)}}$ for h = O(1). If we want to maintain a subexponential-size hitting set of size $2^{s^{\delta}}$ for $\delta \in (0, 1)$, then h can be taken to be at most $c_{\delta}\left(\frac{\log s}{\log \log s}\right)$ where c_{δ} is a constant depending on δ .

4 Computing the Matrix Rank over the Free Skew Field

In this section, we give an efficient algorithm to compute the rank of any matrix over the free skew field whose entries are noncommutative polynomials or rational functions with small linear pencils. Additionally we output a matrix tuple on which the rank is achieved. This is done in two steps. Firstly in Section 4.1, we introduce a blow-up definition for matrix rank over the free skew field extending the results for linear pencils. Next, we show an efficient reduction from the rank computation over the free skew field to the linear case in Section 4.2. The blow-up definition is used to compute the matrix tuple as the witness of the noncommutative rank for such matrices.

4.1 On Blow-up Rank of Matrices over the free skew field

We consider a blow-up definition of noncommutative rank for matrices, denoted ncrank^{*}, over the free skew field. This notion was introduced for linear matrices [13, 24], and for any linear matrix M it coincides with ncrank(M), the inner rank of M [24]. In this section we show that ncrank^{*} coincides with the inner rank (ncrank) for matrices over the free skew field. We focus on square matrices.

Given a matrix $M = (g_{i,j})_{1 \leq i,j \leq m}$ over $\mathbb{F} \lt x_1, \ldots, x_n \blacklozenge$ and $d \in \mathbb{N}$, let

$$M^{\{d\}} = \{M(p_1, \dots, p_n) \mid (p_1, \dots, p_n) \in \mathbb{M}^n_d(\mathbb{F})\}.$$

Define rank $(M^{\{d\}}) = \max_{(p_1,\dots,p_n)} \{ \operatorname{rank}(M(p_1,\dots,p_n)) \}$. We show that rank $(M^{\{d\}})$ is always a multiple of d (Lemma 30). Moreover, this maximum is achieved for the generic matrix of dimension $d \times d$ as shown in Claim 29.

Definition 28. The blow-up rank of the matrix M is defined as

$$\operatorname{ncrank}^*(M) = \lim_{d \to \infty} \frac{\operatorname{rank}(M^{\{d\}})}{d}$$

We first show the existence of this limit and then argue that $\operatorname{ncrank}^*(M) = \operatorname{ncrank}(M)$.

Claim 29. For any $m \times m$ matrix $M = (g_{ij})$ over $\mathbb{F} \lt x_1, \ldots, x_n \succcurlyeq$, and for each $d \in \mathbb{N}$, the maximum rank of the image of M for substitutions from $\mathbb{M}^n_d(\mathbb{F})$ is the rank of M on $d \times d$ generic matrices.

Proof. Let p in $\mathbb{M}^n_d(\mathbb{F})$ be the matrix substitution such that $\operatorname{rank}(M(p)) = r$ is maximum. Let

$$\operatorname{rank}(M(\underline{T})) = r^*,$$

where $\underline{T} = (T_1, \ldots, T_n)$ is an *n*-tuple of $d \times d$ generic matrices. More precisely, $T_k = \left(t_{i,j}^{(k)}\right)_{1 \le i,j \le d}$ and $1 \le k \le n$.

Observe that there is a $r \times r$ submatrix of $M(\underline{p})$ with nonzero determinant. Hence, the determinant of the corresponding submatrix in $M(\underline{T})$ is a nonzero polynomial over $t_{ij}^{(k)}$ variables. Therefore, $r^* \ge r$.

Conversely, there is an $r^* \times r^*$ submatrix of $M(\underline{T})$ whose determinant is nonzero. This determinant is a nonzero polynomial in the $t_{i,j}^{(k)}$ variables. Hence, there is a scalar substitution \underline{p} in $\mathbb{M}_d^n(\mathbb{F})$ for these variables such that the determinant remains nonzero. Clearly, $M(\underline{p})$ is of rank r^* . Therefore, $r \ge r^*$.

Next, we observe that the regularity lemma [24], originally shown for linear matrices, extends to all matrices over the free skew field.

Lemma 30 (A generalization of regularity lemma). For any $m \times m$ matrix $M = (g_{ij})_{1 \leq i,j \leq m}$ over $\mathbb{F} \leq x_1, \ldots, x_n >$ there is a positive integer d_0 such that the maximum rank of the image of M on $d \times d$ matrix algebra for all $d \geq d_0$ is always a multiple of d.

Proof. The proof is straightforward adaptation of the proof for the linear case as presented in Makam's thesis [29, Chapter 4]. Let d_0 be the minimum positive integer such that any nonzero element g_{ij} is not identically zero on $\mathbb{M}_d(\mathbb{F})$ for $d \ge d_0$. By Amitsur's theorem (Theorem 11) the images of the rational expressions g_{ij} are in the universal division algebra U(d). Let \underline{T} be a tuple of generic matrices of dimension $d \times d$. Then by row and column operations in U(d) it is possible to transform the matrix $M(\underline{T})$ into the following form:

$$\begin{bmatrix} I_d & & & \\ & I_d & & \\ & & \ddots & \\ & & & & 0 \end{bmatrix}.$$

If there are exactly r blocks of I_d in the above matrix then clearly its rank is rd.

Claim 31. For any $m \times m$ matrix M over $\mathbb{F} \lt x >$ there is a $d_0 \in \mathbb{N}$ such that for $d \ge d_0$ if $\underline{T} = (T_1, \ldots, T_n)$ is a tuple of generic matrices of size d and $\underline{T}' = (T'_1, \ldots, T'_n)$ is a tuple of generic matrices of size d + 1, then we have that

$$\operatorname{rank}(M(T'_1,\ldots,T'_n)) \ge \operatorname{rank}(M(T_1,\ldots,T_n)).$$

Proof. We prove it by induction on m. Let d_0 be the minimum integer more than m such that any nonzero entry in M is not an identity for the matrix algebra $\mathbb{M}_{d_0}(\mathbb{F})$. The case m = 1 follows from Amitsur's theorem on universal division algebra (Theorem 11) as the image must be invertible. For the induction, suppose a_{ij} is a nonzero entry of M (it must have a nonzero entry). By row and column permutations we can rewrite M as:

$$M = \begin{pmatrix} a_{ij} & b_i \\ c_j & M' \end{pmatrix},$$

where M' is an $(m-1) \times (m-1)$ submatrix of M.

Let $M'' = M' - c_j a_{ij}^{-1} b_i \in \mathbb{M}_{m-1}(\mathbb{F} \not x \not>)$. By some row and column operations we obtain

$$M = U \begin{pmatrix} a_{ij} & 0\\ 0 & M'' \end{pmatrix} V,$$

for invertible matrices U and V over $\mathbb{F} \not \leq x \not>$. Therefore, for any matrix substitution p,

$$\operatorname{rank}(M(p)) = \operatorname{rank}(a_{ij}(p)) + \operatorname{rank}(M''(p))$$

By the induction hypothesis, $\operatorname{rank}(M''(\underline{T}')) \geq \operatorname{rank}(M''(\underline{T}))$. Again by Amitsur's theorem, $\operatorname{rank}(a_{ij}(\underline{T}')) \geq \operatorname{rank}(a_{ij}(\underline{T}))$. Now the claim follows.

Notice that, $\operatorname{rank}(M^{\{d\}}) = \operatorname{rank}(M(\underline{T}))$ and $\operatorname{rank}(M^{\{d+1\}}) = \operatorname{rank}(M(\underline{T}'))$. Therefore,

$$r_{d+1}(d+1) \ge r_d d > (r_d - 1)(d+1).$$

The second inequality follows from the assumption that d is more than m. Hence, $r_{d+1} \ge r_d$. The sequence $\{r_d\}$ is then weakly increasing and bounded. Therefore the limit exists.

It follows that for any matrix M over $\mathbb{F} \lt x_1, \ldots, x_m \blacklozenge$ we have

$$\operatorname{ncrank}^*(M) = \lim_{d \to \infty} \frac{\operatorname{rank}(M^{\{d\}})}{d} = \max_d \frac{\operatorname{rank}(M^{\{d\}})}{d}.$$

Lemma 32. For any $m \times m$ matrix M over the free skew field $\mathbb{F} \lt x_1, \ldots, x_n \succcurlyeq$ we have $\operatorname{ncrank}(M) = \operatorname{ncrank}^*(M)$.

Proof. Let ncrank(M) = r. Then there is an $m \times r$ matrix A and $r \times m$ matrix B over $\mathbb{F} \lt x_1, \ldots, x_n \blacklozenge$ such that $M = A \cdot B$. For any matrix substitution (p_1, \ldots, p_n) of dimension $d \times d$,

$$M(p_1,\ldots,p_n) = A(p_1,\ldots,p_n) \cdot B(p_1,\ldots,p_n).$$

Hence, $\operatorname{rank}(M(p_1,\ldots,p_n)) \leqslant \min\{\operatorname{rank}(A(p_1,\ldots,p_n)), \operatorname{rank}(B(p_1,\ldots,p_n))\} \leqslant rd.$

Therefore, ncrank^{*} $(M) \leq r$.

For the other direction, again let $\operatorname{ncrank}(M) = r$. We need to show that for some $d_0 \in \mathbb{N}$ and all $d \ge d_0$, for the $d \times d$ generic matrix substitution $(T_1, T_2 \dots, T_n)$ we have $\operatorname{rank}(M(T_1, \dots, T_n))$ is at least rd.

Claim 33. For each $r' \leq r$ there is an $r' \times r'$ submatrix $M_{r'}$ of M such that $M_{r'}(T_1, \ldots, T_n)$ is invertible.

Proof of Claim. We will prove it by induction on r'. For r' = 1 we can choose any nonzero entry $g_{i,j}$ of the matrix M. For sufficiently large d the matrix $g_{i,j}(T_1, \ldots, T_n)$ is invertible by Amitsur's theorem (Theorem 11).

By induction hypothesis, let r' = r - 1 and suppose there is an $r' \times r'$ submatrix $M_{r'}$ of M such that $M_{r'}(T_1, \ldots, T_n)$ is invertible. Permuting rows and columns suitably we may assume $M_{r'}$ is the top left submatrix indexed by $\{1, 2, \ldots, r'\}$. Without loss of generality, we can write:

$$M = \left(\begin{array}{c|c} M_{r'} & A \\ \hline B & C \end{array}\right).$$

Let $C' = C - BM_{r'}^{-1}A$ where $M_{r'}^{-1}$ is the inverse of $M_{r'}$ over $\mathbb{F} \lt x_1, \ldots, x_n >$. Then there are invertible matrices U, V corresponding to row and column operations such that

$$M = U\left(\begin{array}{c|c} M_{r'} & 0\\ \hline 0 & C' \end{array}\right) V.$$

Observe that, $r = \operatorname{ncrank}(M) = \operatorname{ncrank}(M_{r'}) + \operatorname{ncrank}(C') = r' + \operatorname{ncrank}(C')$. Hence, ncrank(C') > 0. Let c'_{ij} be a nonzero element of C'. Define the matrix M_r of dimension $r \times r$:

$$M_r = \left(\begin{array}{c|c} M_{r'} & a_j \\ \hline b_i & c_{i,j} \end{array}\right)$$

where b_i is i^{th} row of B and a_j is j^{th} column of A. As $c'_{ij} = c_{ij} - b_i M_{r'}^{-1} a_j \neq 0$ and d is sufficiently large, by Amitsur's theorem (Theorem 11) it follows that $c'_{ij}(T_1, T_2, \ldots, T_n)$ is invertible. Hence $M_r(T_1, T_2, \ldots, T_n)$ is invertible which proves the claim.

Claim 33, shows that there is a submatrix M_r of M such that the rank of $M_r(T_1, \ldots, T_n)$ is rd. Hence ncrank^{*} $(M) \ge r$. Putting it together we have shown ncrank^{*}(M) = ncrank(M) which completes the proof.

4.2 The Rank Computation

In this section, we prove Theorem 5. The idea is to reduce the computation of noncommutative rank of a matrix with skew field entries to noncommutative rank computation of a linear matrix incurring a small blow-up in the size. To show the reduction, we need the following lemma.

Lemma 34. Let $P \in \mathbb{F} \measuredangle x \gg^{m \times m}$ such that,

$$P = \begin{bmatrix} A & B \\ C & D \end{bmatrix},$$

where $A \in \mathbb{F} \lt x >^{r \times r}$ is invertible. Then,

$$\operatorname{ncrank}(P) = r + \operatorname{ncrank}(D - CA^{-1}B),$$

Proof. If Q is an $n \times n$ invertible matrix over $\mathbb{F} \lt x >$ then

$$\operatorname{ncrank}(QP) = \operatorname{ncrank}(PQ) = \operatorname{ncrank}(P).$$

For if P = MN then QP = (QM)N and if QP = MN then $P = (Q^{-1}M)N$. Similarly for PQ. The matrix

$$\begin{bmatrix} A^{-1} & 0 \\ 0 & I_{m-r} \end{bmatrix}$$

is full rank. Similarly, the matrix

$$\begin{bmatrix} I_r & 0\\ -C & I_{m-r} \end{bmatrix}$$

is full rank because

$$\begin{bmatrix} I_r & 0\\ -C & I_{m-r} \end{bmatrix} \begin{bmatrix} I_r & 0\\ C & I_{m-r} \end{bmatrix} = \begin{bmatrix} I_r & 0\\ 0 & I_{m-r} \end{bmatrix}.$$

Hence, ncrank(P) equals ncrank(R) where

$$R = \begin{bmatrix} I_r & 0\\ -C & I_{m-r} \end{bmatrix} \cdot \begin{bmatrix} A^{-1} & 0\\ 0 & I_{m-r} \end{bmatrix} \cdot \begin{bmatrix} A & B\\ C & D \end{bmatrix} = \begin{bmatrix} I_r & A^{-1}B\\ 0 & D - CA^{-1}B \end{bmatrix}$$

Post-multiplying by the invertible matrix $\begin{bmatrix} I_r & -A^{-1}B \\ 0 & I_{m-r} \end{bmatrix}$ we obtain $\begin{bmatrix} I_r & 0 \\ 0 & D - CA^{-1}B \end{bmatrix}$. It is easy to see that its inner rank is $r + \operatorname{ncrank}(D - CA^{-1}B)$.

In the following lemma, we relate the noncommutative rank of a matrix with skew field entries with small linear pencils to the noncommutative rank of a linear matrix.

Lemma 35. Let $M \in \mathbb{F} \lt x >^{m \times m}$ be a matrix where each $(i, j)^{th}$ entry g_{ij} is computed as the $(1, 1)^{th}$ entry of the inverse of a linear pencil L_{ij} of size at most s. Then, one can construct a linear pencil L of size $m^2s + m$ such that,

$$\operatorname{ncrank}(L) = m^2 s + \operatorname{ncrank}(M).$$

Proof. We first describe the construction of the linear pencil L and then argue the correctness. W.l.o.g. we may assume that each linear matrix L_{ij} is $s \times s$ (by padding it, if required, with an identity matrix of suitable size).

Let
$$L = \begin{bmatrix} L_{11} & 0 & \cdots & 0 & B_{11} \\ 0 & L_{12} & \cdots & 0 & B_{12} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & L_{mm} & B_{mm} \\ \hline -C_{11} & -C_{12} & \cdots & -C_{mm} & 0 \end{bmatrix}$$
, (3)

where each C_{ij} is an $m \times s$ and B_{ij} is an $s \times m$ rectangular matrix defined below. Let e_i denote the column vector with 1 in the i^{th} entry and the remaining entries are zero. We define

$$C_{ij} = \left[\begin{array}{c|c} e_i \\ 0 \\ \cdots \\ 0 \end{array} \right] \quad \text{and}, \quad B_{ij} = \left[\begin{array}{c} \frac{e_j^T}{0} \\ \hline 0 \\ \hline \vdots \\ 0 \end{array} \right].$$

To argue the correctness of the construction, we write L as a 2×2 block matrix. As each L_{ij} is invertible (otherwise g_{ij} would not be defined), the top-left block entry is invertible. Therefore, we can find two invertible matrices U, V implementing the required row and column operations such that,

$$L = U \begin{bmatrix} L_{11} & 0 & \cdots & 0 & 0 \\ 0 & L_{12} & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & L_{mm} & 0 \\ \hline 0 & 0 & \cdots & 0 & \widetilde{D} \end{bmatrix} V,$$

for some $m \times m$ matrix D.

Claim 36. The matrix \widetilde{D} is exactly the input matrix M.

Proof of Claim. From the 2×2 block decomposition we can write,

$$\widetilde{D} = [C_{11}C_{12}\cdots C_{mm}] \begin{bmatrix} L_{11}^{-1} & 0 & \cdots & 0 \\ 0 & L_{12}^{-1} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & L_{mm}^{-1} \end{bmatrix} \begin{bmatrix} B_{11} \\ B_{12} \\ \vdots \\ B_{mm} \end{bmatrix} = \sum_{i,j} C_{ij}L_{ij}^{-1}B_{ij}.$$

Observe that, for each $i, j, C_{ij}L_{ij}^{-1}B_{ij}$ is an $m \times m$ matrix with g_{ij} as the $(i, j)^{th}$ entry and remaining entries are 0. Hence, $\tilde{D} = M$.

Notice that the top-left block of L in Equation 3 is invertible as for each $i, j \in [m], L_{ij}$ is invertible. Now the proof follows from Lemma 34.

Proof of Theorem 5. For any matrix $M = (g_{i,j})_{m \times m}$ such that for each $i, j \in [m]$, g_{ij} in $\mathbb{F} \langle x_1, \ldots, x_n \rangle$ has a linear pencil of size at most s, construct a linear matrix L of size $m^2 s + m$ from the previous lemma. We can now compute the noncommutative rank of L using the algorithm of [24] in deterministic poly(s, m, n)-time. Let the rank be r. We now output $r - m^2 s$ to be the noncommutative rank of M. The correctness of the algorithm follows from Lemma 35.

By the equivalence of the inner rank and blow-up rank established in Section 4.1, we know that ncrank^{*} $(M) = r - m^2 s$. Now we use the algorithm in [24] to compute a matrix tuple $\underline{p} \in \mathbb{M}_d(\mathbb{F})$ such that the rank of $L(\underline{p}) = rd$ for some $d = O(m^2 s)$. Clearly rank $(M(\underline{p})) = (r - m^2 s)d$. Therefore, the matrix tuple \underline{p} is also a witness of the rank of M.

5 Efficient Linear Pencils for Inversely Disjoint r-Skewed Circuits

We now prove that an inversely disjoint rational r-skewed circuit of size s has a linear pencil representation of size $O(s^2)$. We first prove a more general result, a composition lemma for linear pencils which implies Theorem 8.

Lemma 37. Let L be an $s \times s$ linear pencil over x_1, \ldots, x_n and y_1, \ldots, y_m . Let $f_{i,j} = (L^{-1})_{i,j}$ for $i, j \in [s]$. Let g_1, \ldots, g_m be rational functions over x_1, \ldots, x_n such that each g_k has a linear pencil L_k of size at most s_k . Then we can construct a single linear pencil \widetilde{L} of size $\sum_{i=1}^m s_i + m + 2s^2 + s$ in poly $(s_1, \ldots, s_m, s, m, n)$ -time such that

$$(\widetilde{L}^{-1})_{2s^2+\widehat{s}+i,2s^2+\widehat{s}+j} = f_{i,j}(\underline{x}, g_1^{-1}, \dots, g_m^{-1}) \quad \text{for } i, j \in [s], \text{ where } \widehat{s} = \sum_{i=1}^m s_i + m.$$

Proof. For each $i, j \in [s]$, $f_{i,j} = (L^{-1}(\underline{x}, y_1, \dots, y_m))_{(i,j)}$ and define $h_{i,j} = f_{i,j}(\underline{x}, g_1^{-1}, \dots, g_m^{-1})$. As the variables y_1, \dots, y_m are indeterminates, we can rewrite each $h_{i,j}$ as the following:

$$h_{i,j} = (L^{-1}(\underline{x}, g_1^{-1}, \dots, g_m^{-1}))_{(i,j)}.$$

We first describe the construction of the linear pencil \widehat{L} and then prove the correctness of the construction. Let \widehat{L} be a linear pencil over x_1, \ldots, x_n of size \widehat{s} where for each $k \in [m]$, there exists $i_k, j_k \in [\widehat{s}]$ such that $g_k^{-1} = (\widehat{L}^{-1})_{i_k, j_k}$. The description of \widehat{L} is given later.

Let us first define two $s \times s$ linear pencils L' and L'' as follows. Fix $i, j \in [s]$. Let $(L)_{i,j} =$ $\alpha_0 + \sum_{k=1}^n \alpha_{k,i,j} x_k + \sum_{k=1}^m \beta_{k,i,j} y_k \text{ . Write } L = L' + L'' \text{ such that } (L')_{i,j} = \alpha_0 + \sum_{i=k}^n \alpha_{k,i,j} x_k \text{ and } (L'')_{i,j} = \sum_{k=1}^m \beta_{k,i,j} y_k.$ We now define \widetilde{L} as a 4 × 4 block linear matrix of size $\widehat{s} + 2s^2 + s$,

$$\widetilde{L} = \begin{bmatrix} I_{s^2} & A_1 & 0 & 0\\ 0 & \widehat{L} & A_2 & 0\\ 0 & 0 & I_{s^2} & A_3\\ \hline A_4 & 0 & 0 & L' \end{bmatrix},$$
(4)

where I_{s^2} is the identity matrix of size s^2 and A_1, A_2, A_3 and A_4 are some rectangular matrices of dimension $s^2 \times \hat{s}$, $\hat{s} \times s^2$, $s^2 \times s$ and $s \times s^2$ respectively. We now define the construction A_1, A_2, A_3 and A_4 . Subsequently in this proof I is used for I_{s^2} .

Let
$$\widetilde{L}_1 = \begin{bmatrix} I & A_1 \\ 0 & \widehat{L} \end{bmatrix}$$
. Then $\widetilde{L}_1^{-1} = \begin{bmatrix} I & -A_1 \widehat{L}^{-1} \\ 0 & \widehat{L}^{-1} \end{bmatrix}$.

We now consider the top-left 3×3 block matrix.

Let
$$\widetilde{L}_2 = \begin{bmatrix} I & A_1 & 0 \\ 0 & \widehat{L} & A_2 \\ 0 & 0 & I \end{bmatrix}$$
. Then $\widetilde{L}_2^{-1} = \begin{bmatrix} \widetilde{L}_1^{-1} & B_1 \\ 0 & I \end{bmatrix}$,
where $B_1 = -\begin{bmatrix} I & A_1 \\ 0 & \widehat{L} \end{bmatrix}^{-1} \cdot \begin{bmatrix} 0 \\ A_2 \end{bmatrix} = \begin{bmatrix} A_1 \widehat{L}^{-1} A_2 \\ -\widehat{L}^{-1} A_2 \end{bmatrix}$.

Define the $s^2 \times s^2$ matrix $A_1 \hat{L}^{-1} A_2 = B_2$. Recall that, $(L'')_{i,j} = \sum_{k=1}^m \beta_{k,i,j} y_k$. We index the rows of A_1 and columns of A_2 as a pair (i, j) for some $i, j \in [s]$. Define for each $(i, j) \in [s] \times [s]$ and $k \in [m], (A_1)_{(i,j),i_k} = \beta_{k,i,j}, (A_2)_{j_k,(i,j)} = 1$ and the other entries are zero. Then,

$$(B_2)_{(i,j),(i,j)} = \sum_{i_k,j_k} (A_1)_{(i,j),i_k} (\widehat{L}^{-1})_{i_k,j_k} (A_2)_{j_k,(i,j)} = \sum_{k=1}^m \beta_{k,i,j} g_k^{-1}.$$

We now define, for each $i, j \in [s]$, $(A_4)_{i,(i,j)} = -1$ and 0 otherwise and $(A_3)_{(i,j),j} = 1$ and 0 otherwise. Since

$$\widetilde{L} = \begin{bmatrix} I & A_1 & 0 & 0\\ 0 & \widehat{L} & A_2 & 0\\ 0 & 0 & I & A_3\\ \hline A_4 & 0 & 0 & L' \end{bmatrix},$$
(5)
where $B_2 = \begin{bmatrix} L' = (A_1 & 0 & 0) \widetilde{L}^{-1} \begin{pmatrix} 0\\ 0 \end{pmatrix} \end{bmatrix}^{-1}$

Now,
$$\tilde{L}^{-1} = \begin{bmatrix} * & * \\ \hline * & B_3 \end{bmatrix}$$
 where, $B_3 = \begin{bmatrix} L' - (A_4 & 0 & 0) \tilde{L}_2^{-1} \begin{pmatrix} 0 \\ 0 \\ A_3 \end{pmatrix} \end{bmatrix}^{-1}$

Simplifying further,

$$B_3 = (L' - A_4 B_2 A_3)^{-1} = L^{-1}(\underline{x}, g_1^{-1}, \dots, g_k^{-1}).$$

Therefore, for each $i, j \in [s]$, $(B_3)_{i,j} = (L^{-1}(\underline{x}, g_1^{-1}, \dots, g_k^{-1}))_{i,j} = h_{i,j}$. Now we construct the linear pencil \hat{L} of size $\hat{s} = \sum_{k=1}^{m} s_k + m$.

For $k \in [m]$, let there are indices $i'_k, j'_k \in [s_k]$ such that $g_k = (L_k^{-1})_{i'_k, j'_k}$. We now define for each $k \in [m]$,

$$\widetilde{L_k} := \begin{bmatrix} L_k & e_{j'_k} \\ \hline -e_{i'_k}^T & 0 \end{bmatrix}$$

Here the vectors e_i are the unit vector. The construction of \hat{L} is now as follows:

$$\widehat{L} = \begin{bmatrix} \widetilde{L}_{1} & 0 & \dots & 0 \\ 0 & \widetilde{L}_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \widetilde{L}_{m} \end{bmatrix}.$$
(6)

Considering the \hat{L}^{-1} as an $m \times m$ block matrix where the i^{th} block is of size $s_i + 1$, it is easy to see that for each $k \in [m]$, the bottom-right corner entry of the k^{th} block of \hat{L}^{-1} is g_k^{-1} . To see this apply Equation 1 with $p_4 = 0$.

Now the proof of Theorem 8 follows easily from Lemma 37.

Proof of Theorem 8. We show that inversely disjoint r-skewed rational functions of height h and of size s have linear pencils of size at most cs^2 for some constant c. We prove it by induction on the inversion height h. For the base case h = 0, the input circuit is a noncommutative ABP and the theorem holds by Proposition 14.

Let $f(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ be an input inversely disjoint r-skewed rational function of height h computed by the circuit C'. Replacing g_i^{-1} by new variable y_i we get a noncommutative ABP $C'(\underline{x}, \underline{y})$ of size $s' \leq s$. Again by Proposition 14, C' can be represented by a linear pencil of size at most 2s'. Let g_1, \ldots, g_m are computed by inversely disjoint r-skewed circuits of size s_1, \ldots, s_m and inversion heights $\leq h - 1$. By the inductive hypothesis each g_k is computable by a linear pencil of size at most cs_k^2 .

Hence by Lemma 37, there is a linear pencil of size S representing $C'(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ which satisfies the following condition.

$$S \leqslant c \sum_{k=1}^{m} s_k^2 + m + 8s'^2 + 2s'.$$

Simplifying further,

$$S \leqslant c \left(\sum_{k=1}^{m} s_k^2 + m + s^{\prime 2} \right),$$

for sufficiently large c. Since the sub-circuits for g_1, \ldots, g_m are disjoint, we get that $(\sum_{k=1}^m s_k^2 + m + s')^2 \leq s^2$. So, $S \leq cs^2$ for some large constant c.

We now prove the following property of the linear pencil constructed in Theorem 8.

Proposition 38. For any inversely disjoint rational r-skewed circuit computing $\mathfrak{r} \in \mathbb{F} \lt x >$ and a tuple of matrix $p \in \mathbb{M}_m^n(\mathbb{F})$ for some finite m, the following are equivalent.

1. \mathfrak{r} is defined at p.

2. For every gate u which is an output gate or a child of an inverse gate, the pencil constructed in Theorem 8 corresponding to the rational expression computed at u is invertible at p.

Proof. We first prove that $(1) \implies (2)$ by induction on inversion height h of \mathfrak{r} . For h = 0, the rational expression \mathfrak{r} is a polynomial f computed by a noncommutative r-skewed circuit (ABP). Note that f is defined everywhere and the linear pencil L constructed in Proposition 14 is invertible everywhere.

Let \mathfrak{r} is of inversion height h. Write $\mathfrak{r} = f(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ and thinking the place holder variables for $g_1^{-1}, \ldots, g_m^{-1}$ as y_1, \ldots, y_m we get $f(\underline{x}, y_1, \ldots, y_m)$ which is a noncommutative ABP over over $\underline{x}, y_1, \ldots, y_m$. The rational functions $g_1^{-1}, \ldots, g_m^{-1}$ are of inversion height $\leqslant h - 1$ (some g_i is of inversion height h - 1 since \mathfrak{r} is of inversion height h).

Let u_1, \ldots, u_m be the set of nodes in the circuit of \mathfrak{r} such that each u_k is a child of an inverse gate computing g_k . Let L be the linear pencil corresponding to $f(\underline{x}, \underline{y})$ from Proposition 14. For some \underline{p} , let $\mathfrak{r}(\underline{p})$ is defined. Therefore, each g_k^{-1} is also invertible at \underline{p} . From the inductive hypothesis, linear pencil L_k (which is constructed by applying Theorem 8) corresponding to g_k is also invertible at \underline{p} . Consider the construction of \hat{L} from Equation 6. It is easy to see from the construction that \hat{L} is also invertible at \underline{p} .

Let \tilde{L} be the linear pencil representation obtained for \mathfrak{r} . We now consider the Equation 5 described in Lemma 37. We can conclude that \tilde{L} is invertible at p if and only if the bottom-right corner block of the inverse, B_3 is defined at p i.e. $L(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ is invertible at p. Define $g_i(\underline{p}) = p'_i$, and $\underline{q} = (\underline{p}, p'_1, \ldots, p'_m)$. Clearly, $f(\underline{q}) = \mathfrak{r}(\underline{p})$. Since L is a linear pencil for f, it is invertible everywhere. In particular, $L(\underline{x}, g_1^{-1}, \ldots, g_m^{-1})$ is invertible at \underline{p} and hence, \tilde{L} is invertible at \underline{p} .

The other direction follows closely from the proof of [22, Proposition 7.1]. We briefly discuss it for completeness. If \mathfrak{r} is not defined at \underline{p} then there exists a gate computing some rational function g^{-1} in the circuit for \mathfrak{r} such that $g(\underline{p})$ is defined but not invertible. So by the induction hypothesis, the linear pencil L_g (constructed from Theorem 8) representing g (at the entry (ℓ_1, ℓ_2)) is invertible at \underline{p} . Now consider the linear pencil \widetilde{L}_g for g^{-1} . From the decomposition, we observe the following.

$$\widetilde{L_g} = \left(\begin{array}{c|c} I & 0\\ \hline -e_{\ell_1}^T L_g^{-1} & I \end{array}\right) \left(\begin{array}{c|c} I & 0\\ \hline 0 & e_{\ell_1}^T L_g^{-1} e_{\ell_2} \end{array}\right) \left(\begin{array}{c|c} L_g & e_{\ell_2} \\ \hline 0 & I \end{array}\right).$$

If $\widetilde{L}_g(\underline{p})$ is invertible, then $g(\underline{p}) = e_{\ell_1}^T L_g^{-1} e_{\ell_2}$ is also invertible. Hence $\widetilde{L}_g(\underline{p})$ is not invertible.

Proof of Corollary 9. Let $\mathfrak{r}(x, g_1^{-1}, \ldots, g_m^{-1})$ be the input inversely disjoint r-skewed circuit of size s. By Theorem 8, we construct a linear pencil \tilde{L} of size $O(s^2)$ for \mathfrak{r}^{-1} . Now by Proposition 38, \mathfrak{r}^{-1} is defined at p if and only if $\tilde{L}(p)$ is invertible. But \mathfrak{r} is nonzero if and only if \mathfrak{r}^{-1} is defined [1]. So for nonzero testing of \mathfrak{r} , it is enough to apply the singularity testing algorithms in [24] on the linear pencil \tilde{L} in white-box case. For the black-box case one can use the algorithm in [13]. In fact the result in [24] also gives the dimension upper bound of $O(s^2)$ for the tensoring matrices on which \tilde{L} should be tested for singularity. This also leads to randomized polynomial-time black-box algorithm that simply substitutes the variables randomly from matrices of dimension $O(s^2)$ over sufficiently large fields.

6 Future Directions

Our work raises the following questions for further research:

- The most important question is to obtain an *unconditional derandomization* of the blackbox RIT problem. The current best known result is a quasipolynomial-time black-box RIT algorithm for rational formulas of inversion height at most two [2].
- Theorem 4 opens up a new motivation to further study the Conjecture 2. In [4], it is shown that a nonzero noncommutative polynomial of sparsity s can not be an identity for some $k = O(\log s)$ dimensional matrix algebra. This solves a special case of the conjecture and the proof uses automata theoretic ideas very crucially. Can we improve these techniques to settle the conjecture completely?
- The effective use of Higman's trick has found new applications in randomized polynomialtime factorization algorithm for noncommutative formulas [3]. The proof of Theorem 5 does not use Higman's trick. It would be interesting to see whether such ideas can be applied elsewhere.
- Can we exactly characterize (up to a polynomial-size equivalence) the expressive power of linear pencil representations for some sub-class of rational circuits? In this paper, we show that inversely disjoint r-skewed circuits have polynomial-size linear pencils. This gives $ID-R-rSC \subseteq LR$. It would be very interesting to prove that rational r-skewed circuits can be expressed by polynomial-size linear pencils. In other words, prove that R-rSC = LR.

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